AMENDMENTS TO THE SPECIFICATION

Please replace Paragraph [0026] with the following paragraph rewritten in amendment format:

[0026] Figure [[2]] 1 is a structural arrangement of the torque transmission device 5. The torque transmission device 5 includes the coupling 6. The coupling 6 has a coupling housing 7, as first coupling element, arranged coaxially around a coupling hub 8, which forms a second coupling element. The coupling hub 8 connects to a drive journal of the implement 3 shown in Fig. 2. The coupling hub 8 transmits a rotational movement from the tractor, via the universal joint shaft 1, to the implement 3.

Please replace Paragraph [0028] with the following paragraph rewritten in amendment format:

[0028] The coupling housing 7 has a connection plate 10. The connection plate 10 includes threaded bores 11 distributed along the circumference around the longitudinal axis 14. On this connection plate 10, a support plate 12 is fixed by means of interposition of six first driving elements 15, formed as distance sleeves. Screws 16 pass through bores 13 in the support plate 12 and through bores of the first driving elements 15. The screws 16 are screwed into the threaded bores 11 of the connection plate 10. A space 17 is between the support plate 12 and the connection plate 10. The support plate 12 has a bearing bore 18 which is ~~centred~~ centered on the longitudinal axis 14.

Please replace Paragraph [0029] with the following paragraph rewritten in amendment format:

[0029] The torque transmission device 5 further includes a driving member 20. The driving member 20 has a driving member portion 21. Six tooth-like second driving elements 22 or rotational abutment project around the circumference of the driving member portion 21, in this embodiment. Different numbers of second driving elements are also possible. The second driving elements 22 are distributedly arranged around the longitudinal axis 14. As seen in Figure [[4]] 3, a total of six second driving elements 22 are provided. Further, the driving member 20 has a bearing portion 24. The bearing portion 24 is cylindrically formed and fits to the bearing bore 18 of the support plate 12. The driving member 20 comprises two universal joint yoke arms 25 belonging to the universal joint which forms part of the universal joint shaft 4 of Fig. 1.